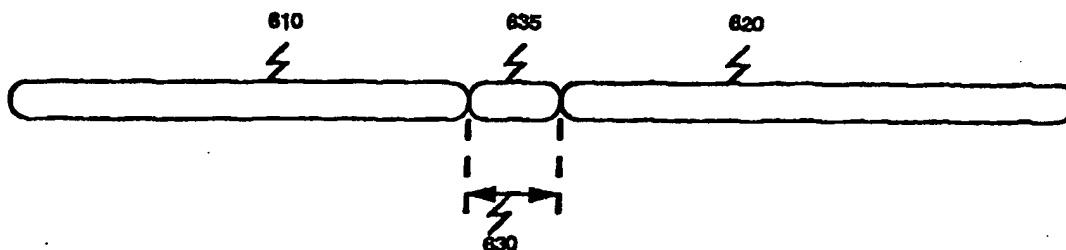


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(54) Title: **CCD-BASED BAR CODE SCANNER**

## (57) Abstract

A bar code scanning system for a conveyor system in which a first conveyor (610) and a second conveyor (620) are disposed apart from each other by a small gap region (635). A light emitting device is positioned in the gap (635) underneath a top surface of the first and second conveyors (610, 620), and the light emitting device shines light onto bar code labels on a bottom side of objects as the objects traverse from the first conveyor (610) to the second conveyor (620). A light receiving device is also positioned in the gap (635), and the light receiving device receives reflected light from the bottom side of the objects due to the light being shined on the objects by the light emitting device. The gap (635) is covered by a glass or plastic plate, so as to allow light to pass substantially therethrough.

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## CCD-BASED BAR CODE SCANNER

### Background of the Invention

#### 1. Field of the Invention

5 The present invention relates to a CCD-based bar code scanning system. In particular, the present invention relates to a CCD-based bar code scanning system that provides a plurality of different scan patterns from stored bar code return data from one or more CCD cameras.

#### 2. Description of the Related Art

10 Bar codes are used in a wide variety of applications for retrieving information, such as price, from objects. In this respect, bar code scanners are of widespread use in grocery stores and department stores, for both inventory control and for point-of-sale (POS)  
15 transactions.

A bar code normally includes several bar code characters. A bar code character is a group of lines (bars) and spacings that represent a single number or letter. A bar code symbol is a collection of several bar  
20 code characters which represent an identification of a particular object. The lines of the bar code can vary, for example, in a range from about 1/8" to 1" in height, and from about 1 to 50 mils in thickness. The spacings between the lines of the bar code symbol may be of  
25 various widths, with the variations in the spacing being one indication of the type of bar code characters making up the bar code symbol.

Typically, bar codes are read by a bar code scanner by illuminating the bars and spacings in a sequential  
30 manner, with the bars absorbing light and the background spacings reflecting light. This results in a pattern of reflections and nonreflections that is sensed by a light

detecting circuit resident in the bar code scanner. The light detecting circuit provides an input to a digital processor, which interprets this input into a digital word.

5       A bar code label may be read by a scanner that detects reflected and/or refracted light from the bars and spaces that comprise the bar code characters. One conventional method of illuminating the bar code label is by the use of a scanning laser beam, in which case a beam  
10       of light sweeps across the bar code label, and an optical detector (such as a photo-diode detector) detects the reflected light. The detector generates an electrical signal having an amplitude determined by the intensity of the collected light.

15       Another conventional method for collecting return light from the bar code label is by the use of an array (commonly known as a charge-coupled device or CCD) of optical detectors connected to an analog shift register. In such a method, as with a scanning laser, an electrical  
20       signal is generated having an amplitude determined by the intensity of the collected light. In either the scanning laser method or the CCD method, the amplitude of the electrical signal has one level for dark bars and another level for light spaces. As the bar code label is  
25       scanned, positive-going and negative-going transitions in the electrical signal occur, signifying transitions between bars and spaces. Techniques are known for detecting edges of bars and spaces by detecting the transitions of the electrical signal. One such technique  
30       is described in U.S. Patent Number 5,382,783, issued to Edward Bremer, assigned to PSC Inc., which is incorporated in its entirety herein by reference. Another such technique is described in U.S. Patent Number 5,298,728, issued to Randy Elliott et al. assigned to  
35       Spectra-Physics Scanning Systems (now PSC Scanning, Inc.), which is incorporated in its entirety herein by reference. Techniques are also known for determining the widths of bars and spaces based on the relative location

of the detected edges and decoding the information represented by the bar code.

In order to scan a bar code, the bar coded items may be moved manually in front of the scanner or automatically on a moving conveyor belt. Alternatively, the scanner may be held by an operator and directed at a bar code. Some bar code labels may be "truncated" (that is, have short bars relative to the length of the label). Conventional scanning devices require careful operation to attain a high probability of a successful read and are difficult to use with truncated labels because of the difficulty of attaining proper orientation of the bar code label with respect to the scanner. Randomly oriented items on a conveyor belt must have very long bars relative to the length of the code in order to have a high probability of being read.

Handheld single line scanners, either laser or CCD-based, require that an operator aim and orient the scanner relative to the bar code so that the scan line is substantially perpendicular to the bar code edges. Such operation requires some care on the part of the operator and reduces productivity. Furthermore, these devices are sensitive to label defects, as detection of bar and space edges is typically done along a single narrow scan line. To maximize the productivity of the operator, minimize stresses due to repetitive motions of the operator's body, and minimize sensitivity to label defects, it is therefore desirable to read bar codes that may be positioned at any orientation relative to the scanning device.

Conventional POS scanning systems typically require an operator to handle each item (or handle a portable scanner) in order to orient the item to the scanner for scanning. A conveyor belt system may be used to reduce the amount of effort required. Current conveyor systems, however, have difficulty scanning items that have bar code labels on the bottom surface of objects on the conveyor. Consequently, the operator must position the

item so the bar code label is not facing the top surface of the conveyor, or must take each item from a feed conveyor, scan it, and place it on a takeaway conveyor. Conventional systems generally do not allow scanning of all surfaces of the packages, requiring the operator to position the packages so the bar code is on the surfaces that can be scanned.

Various methods have been used to attempt to read a bar code label at any orientation to the scanner in a minimum number of passes. Thus, multi-line or complex-pattern laser scanners exist that can read bar codes over a range of orientations. In general, these devices utilize pattern-forming mirrors or holographic beam deflection elements, and are hence larger than other scanners and require more components as the scan pattern complexity increases. These scanners typically require a complex mechanism to sweep the laser beam in a predetermined pattern and therefore require additional and costly mechanical parts, increasing proneness to wear.

In another type of conventional scanner, a two-dimensional array of CCD elements is used to obtain an entire image of the bar code at one time. However, the drawback of these devices is that large amounts of memory are needed to store the image to be processed, and large amounts of computation are needed to extract the edge location data from the stored image. Further, complicated algorithms are necessary to determine the orientation and characteristics of the bar code label.

U.S. Patent Number 5,446,271, issued to Gerald Cherry et al., and assigned to Spectra-Physics Corporation (now PSC Scanning, Inc.), discloses a technique for creating a plurality of virtual scan lines based on stored image data from a two-dimensional or one-dimensional CCD camera. In this system, an optical sensor has a planar imaging region, which may correspond to an imaging region of a two-dimensional CCD camera, or which may correspond to a one-dimensional CCD camera with the second dimension

created by raster input due to relative motion of the optical sensor with respect to a bar code label.

An exemplary bar code that may be scanned by the system as disclosed in U.S. Patent Number 5,446,271 is shown in Figure 1, where the bar code label 11 may be comprised of one or more smaller pieces 21 that are the minimum size necessary for decoding (i.e., minimum decodable pieces). A minimum decodable piece 21 of bar code label 11 has a height  $H_L$  and a width  $W_L$ . When scanned, the bar code label 11 may not necessarily be oriented to the optical sensor at a perfectly flat angle, but may be inclined at an angle  $A_L$  with respect to the optical sensor, as shown in Figure 2. The result may be that the projection of the image of the bar code label 11 (or a minimum decodable piece 21 thereof) is distorted when it hits the imaging region 13. The projection 20 of the label or piece image has a height  $H$  (the "apparent height") and a width  $W$  (the "apparent width"). If the relative dimensions  $H_L$  and  $W_L$  of the minimum decodable piece are known, and the angle of inclination  $A_L$  is also known, the size of the projection 20 onto the imaging region 13 may be determined. U.S. Patent Number 5,446,271 describes in detail the manner of determining the size of the projection 20. For example, universal product codes (UPC codes) are "over square" codes, in which the height of the bars in each piece of the code is greater than the width of the piece of the code.

The bar code label 11 also has a minimum element width  $W_E$  of the bar and space elements comprising the label 11. The minimum apparent bar code element width  $W_{MIN}$ , which affects the preferred characteristics of the imaging region 13, may be derived from the minimum bar code element width  $W_E$ , as described in U.S. Patent Number 5,446,271. The Cherry patent states that "ten or more pixels per element would be desirable in a UPC code reader."

In the system described in U.S. Patent Number 5,446,271, when a CCD-based reader reads a particular

region that it covers, only values from certain elements in the CCD array are stored in a memory, for later processing to determine if reflections from a bar code have been received. For example, Figure 3A shows how  
5 horizontal scan lines are created, with only the "\*" pixels being stored in a memory, and Figure 3B shows how diagonal scan lines are created, with only the "\*" pixels being stored in the memory. By this system, a plurality of different scan lines may be created and stored in the  
10 memory (see Figure 4), with one of those scan lines (hopefully) properly oriented so as to read a bar code that may be positioned in any particular orientation with respect to the laser scanning device and the CCD-based reader. Cherry also discloses an image acquisition unit  
15 positioned to receive return light from an object on a conveyor as that object passes over a gap between a first belt and a second belt. The image acquisition unit is positioned in the gap, beneath the belts.

While the above-described Cherry patent is very  
20 useful in detecting bar codes at any particular angle, there are still issues with respect to memory size and CCD-based array size that could be improved upon, as well as orientation of the CCD-based reader itself with respect to a bar code being scanned.

25

### Summary of the Invention

It is an object of the present invention to provide a bar code reader that is capable of reading bar codes at any particular orientation with respect to the bar codes,  
30 even at a position below the bar codes, such as where the reader is positioned in a plate-covered gap between two separate conveyors on a conveyor belt system, with the plate allowing light to pass substantially therethrough.

It is another object of the invention to provide a  
35 system that can transform a two-dimensional array of stored image data from a CCD-based camera into an X-



scanning pattern that is suitable for UPC codes and the like.

It is still another object of the invention to provide a system that can provide a timing capability to read a two-dimensional array of stored image data so as to create a plurality of scan lines from the stored image data.

It is yet another object of the invention to provide a system that utilizes a CCD-based camera together with optics so as to lessen the number of cameras required to scan a particular region with a particular desired level of bar/space resolution.

These and other objects of the invention may be accomplished by a bar code scanning system, which includes a first conveyor for moving objects from a first location to a second location, and a second conveyor for receiving the objects from the first conveyor and for moving the objects to a third location. The system further includes a light emitting device positioned in a gap underneath a top surface of the first and second conveyors, the light emitting device configured to shine light onto bar code labels on a bottom side of objects as the objects traverse from the first conveyor to the second conveyor. The system also includes a light receiving device positioned in the gap, the light receiving device configured to receive reflected light from the bottom side of the objects due to the light being shined on the objects by the light emitting device. The system still further includes a plate disposed entirely within the gap, the mirror-like unit having a top surface disposed along a same plane as the top surfaces of the first and second conveyors. The top surface of the plate provides a substantially continuous surface with the top surfaces of the first and second conveyors as the objects traverse from the first location to the third location.

The above-mentioned objects and other objects may also be accomplished by a bar code scanning method, which

includes a step of scanning a particular location with a CCD camera having a plurality of pixels each positioned to receive reflected light from a distinct portion of the particular location. The method also includes a step of  
5 providing separate control for a plurality of different scan lines to be generated. The method further includes a step of outputting data from a different subsets of the plurality of pixels based on the separate control provided in the second step, so as to provide a plurality  
10 of virtual scan lines, respectively. The method still further includes a step of determining if a bar code has been scanned by simultaneously decoding the data from each of the different subsets.

The above-mentioned objects and other objects may  
15 also be accomplished by an apparatus for scanning a bar code label, which includes a CCD camera configured to provide a linear array of scan output corresponding to a particular region currently being scanned. The apparatus also includes a controller connected to the CCD camera  
20 and configured to output the linear array of scan output to a particular region of a memory. The apparatus further includes a signal processor connected to the memory and configured to output data from particular memory locations of the memory so as to create at least  
25 one virtual scan line. The apparatus still further includes a decoder configured to determine if data corresponding to the virtual scan line corresponds to a real bar code.

The above-mentioned objects and other objects may  
30 also be accomplished by a bar code scanning system for a conveyor, which includes a laser light source configured to output laser light, the laser light source being rotatably mounted to a housing. The system also includes a CCD-based camera configured to receive light from a  
35 particular region. The system further includes a lens disposed between the CCD-based camera and the conveyor, the lens being mounted to the housing and capable of linear movement with respect to the conveyor and the CCD-

based camera. The system still further includes a height measuring device configured to determine a height of an object as the object passes by the height measuring device and to output a height signal indicative thereof.

5 The system also includes a processing unit configured to output a first signal to rotate the laser light source to a first position and to output a second signal to linearly move the lens to a second position. The first and second positions are such that the laser light source and the CCD-based camera are focused to an area

10 corresponding to the height of the object.

#### Brief Description of the Drawings

The above-mentioned objects and advantages of the invention will become more fully apparent from the

15 following detailed description when read in conjunction with the accompanying drawings, with like reference numerals indicating corresponding parts throughout, and wherein:

Figure 1 shows a typical bar code label;

20 Figure 2 is a diagram of an optical sensor positioned with respect to an imaging region;

Figure 3A shows how a virtual horizontal raster line may be created from stored image data in a conventional bar code scanning device;

25 Figure 3B shows how a virtual diagonal raster line may be created from stored image data in a conventional bar code scanning device;

Figure 4 shows a plurality of virtual scanning lines that may be created from stored image data, in a

30 conventional bar code scanning device;

Figure 5 shows in block diagram form a bar code scanning device according to a first embodiment of the invention;

35 Figure 6 shows a side view of the bar code scanning device according to the first embodiment, utilized with a conveyor system;

Figure 7 shows a view of the bar code scanning device according to the first embodiment in a widthwise direction, looking down from the top of a conveyor system utilized with the bar code scanning device;

5        Figure 8 shows an alternative construction of the bar code scanning device according to the first embodiment, where optics are utilized;

Figure 9 shows in block diagram form the details of a conversion module used in the first embodiment;

10       Figure 10 shows the timing sequence of how data is written into a memory in the conversion module used in the first embodiment;

Figure 11 shows an alternative configuration of the conversion module used in the first embodiment;

15       Figure 12 shows in block diagram form a raster conversion implementation used in the first embodiment, that is capable of handling outputs from four line scanning cameras at one time;

20       Figure 13 shows in block diagram form a bar code scanning device according to a second embodiment of the invention, when viewed from above a conveyor;

25       Figure 14 shows the laser light source and the CCD-based camera being positioned in either of two positions, according to the second embodiment of the invention, when viewed directly in front or in back of a conveyor;

Figure 15 shows in block diagram form a bar code scanning device according to a third embodiment of the invention;

30       Figure 16 shows a configuration of a memory portion of the common logic unit according to the third embodiment of the invention; and

Figure 17 is a flow diagram of the steps performed for the bar code scanning device according to the third embodiment.

### Detailed Description of the Preferred Embodiments

Preferred embodiments of the invention will be described in detail below, with references to Figures 5 through 17. Figure 5 shows in block diagram form a first embodiment of the invention, in which a plurality of CCD-based cameras 510A - 510C are used to receive return light from a bar code label (not shown), where the return light is due to light directed onto the bar code label from corresponding laser light sources 520A - 520C. Each camera 510A - 510C has a lens associated with it, as shown in Figure 5. Each camera 510A - 510C is connected to an associated conversion module 530A - 530C, which receives the image data output from its associated camera, and which sends out only a certain portion of the stored data to a decoder unit 540. The decoder unit 540 performs decoding of the received data, so as to determine if a bar code label has been scanned or not. Such a system may be utilized with a conveyor belt system (in which boxes having bar code labels pass by the system), or without a conveyor belt system, depending on the needs of a user of the system. For ease in explanation, the first embodiment of the invention will be described hereinbelow with reference to a conveyor belt system.

In Figure 6, a first conveyor 610 and a second conveyor 620 are shown, with a gap 630 between an end of the first conveyor 610 and an adjacent end of the second conveyor 620. In the first embodiment, a component 635 is fitted into the gap 630, so that there is provided a substantially continuous surface between one end of the first conveyor 610 and the adjacent end of the second conveyor 620. The component 635 is of a construction such that it allows light to pass therethrough, such as a clear plastic or glass plate. Alternatively, the gap 630 may be configured of a small enough size (e.g., 1/2 inch in width), without having any component disposed within the gap 630. Due to the small width of the gap

630, items passing along the top surface of the conveyors 610 and 620 would not fall into the gap 630. Thus, even very small items can pass from the first conveyor 610, across the gap 630, and onto the second conveyor 620.

5 In conventional bar code scanning systems using conveyor belts, scanners may be disposed along five separate directions -- i) in front of the conveyors, ii) behind the conveyors, iii) to one side of the conveyors, iv) to the other side of the conveyors, and v) above the  
10 conveyors. These systems, known as five-sided scanning systems, work well to detect and decode bar code labels that may be disposed at either: i) the front of a box on the conveyor, ii) the back of the box on the conveyor, iii) one side of the box on the conveyor, iv) the other  
15 side of the box on the conveyor, or v) the top of the box on the conveyor. However, if a bar code label is disposed on the bottom side of the box on the conveyor, it has to be manually repositioned by an operator prior to scanning the label, so that one of the five scanners  
20 may be able to detect the bar code label.

However, in the first embodiment, this manual movement by an operator is not required, since a scanner disposed within the gap 630 (or beneath the glass plate or plastic in the gap 630) can detect bar code labels  
25 along a sixth side. Thus, the first embodiment corresponds to a six-sided scanning system.

Assuming that the conveyors 610 and 620 have a width of approximately 30 inches, and assuming that the bar code labels have minimum-width bars and spaces of 15  
30 mils, it is important to determine the number of CCD-based cameras that need to be disposed within the gap 630 so as to read a label on the bottom of a box positioned anywhere on the gap 630 (that is, anywhere on a length-wise direction on the gap 630) between the conveyors 610  
35 and 620.

Assuming that one CCD-based camera has  $2048 = 2^{11}$  pixels, and assuming that it is desired to have at least three pixels per minimum width bar/space, then that one

camera can detect return light over a  $2048 * 15 \text{ mils}/3 = 10.24$  inches. Thus, three separate CCD-based cameras, spaced coaxially with respect to each other as shown in Figure 7, are needed to cover the entire 30 inch-width of the conveyors 610 and 620. In this configuration, there is provided a laser light source 520A - 520C for each of the CCD-based cameras 510A - 510C. Each of the laser light sources 520A - 520C is fixedly positioned in the gap 630 underneath the first and second conveyors 610, 620. Each of the laser light sources 520A - 520C is positioned to output laser light through the gap 630 and onto a particular region 10" wide or so region on the gap 630 of the 30 inch-wide conveyor system. The light from the laser light sources 520A - 520C reflects off of an object, and is received by a corresponding one of the CCD-based cameras 510A - 510C.

In the above example, it is assumed that each pixel of a CCD-based camera is capable of receiving light from a 5-mil wide region. However, depending on the type of CCD-based camera and the distance that the camera is positioned with respect to the imaging region, this may not always be the case. In those situations, optics 860 are provided between the imaging region (that is, the top surface of the glass plate or plastic disposed in the gap 630) and the cameras, as seen in Figure 8. These optics 860 have a level of magnification sufficient to provide the desired regional coverage for the pixels of the cameras. In an alternate configuration, the optics 860 may serve as both a magnifying and/or focusing device, as well as a cover plate for the gap region 630 (i.e., element 635 may comprise the optics). Preferably, the top surface of the glass plate or plastic disposed in the gap 630 has a hard coating, such as a ruby coating or other type of scratch-resistant coating, so as to resist scratching from objects as they pass over the glass plate or plastic from the first conveyor 610 to the second conveyor 620.

For example, if a camera has 1024 pixels, with each pixel capable of receiving light from a 2.5-mil wide region when the camera is positioned 1 inch away from the imaging region, then the optics 860 have to provide a

5 "times 2" (x2) magnification, so as to provide a 5 mil width for each pixel. This 5 mil width corresponds to the three pixel per minimum bar/space requirement that was set as a requirement for the system. In this instance, with the optics 860, one camera is capable of

10 covering a region on the conveyor of  $1024 \text{ pixels} \times 2.5 \text{ mils/pixel}$  (without optics magnification)  $\times 2$  (optics magnification) = 5.1 inches. Thus, six CCD cameras would be required in order to cover the entire 30-inch width of the conveyor. Similar to the optics used with the CCD

15 cameras, additional optics may be used with the laser light source, as needed.

In the first embodiment, a requirement of three pixels per minimum width bar/space is utilized, but one of ordinary skill in the art will recognize that any

20 number of pixels per minimum width bar/space may be utilized while remaining within the scope of the invention, as long as at least one pixel per minimum width bar/space is met. Of course, the more pixels per minimum width bar/space one has, the better the

25 information that is being sent to the decoder, so as to achieve a better probability of correctly decoding a bar code label. Also, having more than one pixel per minimum width bar/space is useful for properly decoding bar code labels that have print imperfections on them.

30 In the embodiment of Figure 5, the decoder unit 540 is only capable of receiving X-scan patterns from one or more collector units, and so the conversion modules 530A - 530C must reconfigure the two-dimensional data from each of the cameras 510A - 510C so as to provide the X-

35 scan patterns to the decoder unit 540. One way of achieving this scan conversion would be to utilize a system similar to that disclosed in U.S. Patent Number 5,446,271. In the present invention, however, all of the



pixel data is read into a memory within each of the conversion modules 530A - 530C, but only data from predetermined regions of the memory are outputted to the decoder module 540. Since the X-scan pattern corresponds to two 45-degree diagonal lines oppositely oriented, one diagonal line of the X-scan pattern would correspond to the first element in the first column of an  $n$ -by- $n$  memory (that is, a memory capable of storing  $n^2$  bits of data), the second element in the second column of the memory, . . . , the  $n^{\text{th}}$  element in the  $n^{\text{th}}$  column of the memory. Similarly, the other diagonal line of the X-scan pattern would correspond to the  $n^{\text{th}}$  element of the first column, the  $(n-1)^{\text{st}}$  element of the second column, . . . , the first element of the  $n^{\text{th}}$  column. A corresponding portion of the X-pattern is provided to the decoder unit 540 by each conversion module.

A block diagram of a conversion module, such as 510A, is shown in Figure 9. A camera interface unit 905 is coupled to the associated camera (either 510A, 510C, or 510C). A direct memory access controller (DMA) 910 provides the control for sending the pixel image data from the camera interface 905 to a memory 920. The memory 920 is configured as an  $n \times n$  memory, having  $n^2$  memory locations (e.g.,  $10 \times 10 = 100$  memory locations). In the first embodiment, memory 920 is a random-access-memory, and is configured as a 2048-word by 2048-word memory, which provides a symmetric block corresponding to a 10.24" square. The data corresponding to the two diagonal lines making up the X-scan pattern are read by a digital signal processor (DSP) 930 that is connected to the memory 920. DSP 930 reads the corresponding X-scan pattern data from predetermined memory locations in the memory 920 by using a program retrieved from an EEPROM 940. DSP 930 provides the coordination between the camera data and downloads to the decoder unit 540. The program stored in EEPROM 940 provides the means by which the DSP 930 retrieves the proper memory locations from

the memory 920, so as to output X-scan pattern data to the decoder unit 540 (see Figure 5).

5       The basic function of the system according to the first embodiment is to convert the sequential raster reads from the camera to an X pattern format familiar to the decoder unit 540. The array in the memory 920 will model a picture of what has passed by the camera for a finite period of time. It will also be cyclical, thereby causing the imaged barcode to traverse through the diagonal read elements in the array. Basically, the process involves writing into memory 920 in sequence what the camera images, and then at predefined periods reading the diagonals of the array. The whole process thus involves proper timing in reading and writing to/from memory 920.

15       The writing into memory 920 (camera data) will begin at an initial point (0), and will continue until the end of the array,  $2^{24} - 1$  words. At this point, the writing will restart at the initial point again. Each row is comprised of 2048 words along with a row pointer that is updated after each row is completed. The row pointer becomes effectively the end of the memory array. The row pointer also functions as an element for generating the X-pattern, since it will effectively fold the memory addressing around at the lower and upper limits.

25       The reading of the diagonal elements will simulate the X pattern for an omnidirectional scanner, top left to bottom right, followed by top right to bottom left. This is achieved through subtraction and addition of one memory address to both the column and row element. For example, the first diagonal element is generated by adding  $2048 + 1$  to the last memory address starting at the row pointer. This is repeated 2048 times for each diagonal element. The other diagonal is generated by

30       2048 - 1.

35       Assuming a writing rate of 125  $\mu$ seconds per row (2048 words) and 1 millisecond for each X pattern (4096 words), the ratio for input data rate to output data rate is 4:1.

Therefore, for each four writes to the array, there will be one read to the decoder unit 540.

5 In actual performance, the writing of the row data will primarily be controlled by the conveyor belt speed, where the velocity of the conveyor belt will be determined by a tachometer. The derivative of the velocity provides the necessary frame clocking for a 5 mil resolution.

10 The DSP 930 may be a model TMS320C3x or any other type of digital signal processor. Model TMS320C3x is a 32-bit processor, with the capability of addressing 16M words. Should the raw camera video be digitized for eight bits, the TMS320C3x can handle four cameras simultaneously.

15 In the first embodiment, lasers are provided as the light emitting sources 520A - 520C, since a white light source (or sources) would typically not suffice for illuminating a bar code label positioned upwards with respect to a light emitting and light receiving unit. A  
20 laser source may be conveniently used within the small gap region between conveyors and has a better signal-to-noise ratio than a white light source (such as a lamp).

As explained above, each conversion module unit 530A - 530C converts the sequential raster read from its  
25 associated CCD camera 510A - 510C to a diagonal format familiar to the decoding unit 540. In the first embodiment, the decoding unit 540 is a 990 E-box manufactured by LazerData (now part of PSC Inc). The memory array 920 stores a snapshot of what has passed by  
30 the CCD cameras 510A - 510C for a finite period of time. The memory array 920 is cyclically updated. The imaged barcode essentially traverses through the diagonal read elements in the memory array 920.

35 In the first embodiment, as shown in Figure 10, pixel elements from the CCD camera 510A - 510C are written into a first region (shown as a first column) of the memory 920 by the DMA 910 at a first sampling instant in time  $t_1$ . In the discussion given hereinbelow, it is assumed

that each CCD element corresponds to one pixel, with one bit assigned for each pixel. Of course, one of ordinary skill in the art will recognize that the system according to the invention is operable with a system employing more than one pixel per CCD element and/or more than one bit assigned for each pixel.

For a one-dimensional CCD camera, at a particular sampling instant in time, one entire column of the memory 920 is written into. At a second sampling instant in time  $t_2 = t_1 + \Delta t$ , a next column (disposed just to the right of the previously-written-into column in Figure 10) is written into by the DMA 910. This procedure is continued until the  $n$ th (last) column of the memory 920 is written into by the DMA 910 at the  $n$ th sampling instant in time  $t_n = t_1 + n \cdot \Delta t$ . When the  $n$ th column is written into, then the DSP 930 is notified, and performs its reading of particular memory locations within the memory 920 so as to achieve the X-scan pattern to be sent to the decoder unit 540.

The memory 920 can then be reset at this time, by a signal from the DSP 930 indicating that it no longer needs the information stored in the memory 920. Once reset, the memory 920 is ready to receive the data from the  $(n+1)$ -st instant in time  $t_{n+1} = t_1 + (n+1) \cdot \Delta t$  to be written into the first column of the memory 920 by the DMA 910. As an alternative, the memory 920 need not be reset, and so the pixel data corresponding to the  $(n+1)$ -st instant in time  $t_{n+1}$  is written over the data from the first instant in time  $t_1$ , the pixel data corresponding to the  $(n+2)$ -st instant in time  $t_{n+2}$  is written over the data from the second instant in time  $t_2$ , etc. When the  $2n$ -st instant in time  $t_{2n}$  occurs (where the data from the  $2n$ -st instant in time  $t_{2n}$  is written over the data from the  $n$ -st instant in time  $t_n$ ), the DSP 930 can then retrieve the data from the particular locations in the memory 920 again, in a manner similar to what it did after the  $n$ -st instant in time  $t_n$ .

Another important feature of the present invention is to have a memory system that is fast enough to provide for a particular system requirement, such as a conveyor speed. As an example, assume that the a system requires the reading of 15 mil bar codes moving on a conveyor at 150 feet per minute (fpm). In order to have a safety margin, a CCD camera will be designed to have a resolution of 5 mil at 200 fpm. Note that a 5 mil resolving capability on the CCD camera will only accurately show a minimum of 10 mil bars because of the Nyquist criteria (i.e., need to sample at a rate of at least twice the highest frequency component of the input waveform). The CCD camera to be used in the system are designed for a maximum clock rate of 20 MHz and have a linear array of 2048 pixels.

For a conveyor belt speed of 200 ft/min = 40 inches/sec, and for a scan resolution of 5 mil, we get:  
$$40 \text{ in/sec} / 5 \text{ mil} = 8000 \text{ scans/second, which is equivalent to a scan rate of } 125 \text{ microseconds/scan.}$$
$$2048 / 125 \text{ microseconds} = 16.4 \text{ MHz for the clock rate required on the CCD cameras.}$$

The above values hold true for both the vertical and horizontal axes. This also defines the memory array size, 2048 x 2048 bytes, or a total of 4.2 Mbytes. By taking the reciprocal of the clock rate (60 nsec), we are provided with the memory speed requirement.

The output of the module needs to comply with the requirements of the decoder unit, which we will assume has a scan rate of 1 msec per channel. Since the diagonal of the memory array are being read out, the total bytes are:

$$2 \times (2048 \text{ bytes} \times 1.414) = 5792 \text{ bytes to be read every } 1 \text{ milliseconds (1.414 equals the square root of two). This is equivalent to a clock rate of } 5.8 \text{ MHz, or a minimum timing resolution of } 170 \text{ nsec.}$$

While the memory 920 is depicted as a single memory in Figures 9 and 10, it may alternatively correspond to a plurality of memories 1010, 1020, 1030, as shown in

Figure 11, with memory 1010 receiving pixel image data from the first camera 510A, memory 1020 receiving pixel image data from the second camera 510B, and memory 1030 receiving pixel image data from the third camera 510C (where three cameras are needed to cover an entire width of a conveyor belt, for example). Each memory corresponds to a particular region of a total memory 920 that corresponds to the combination of the memories 1010, 1020 and 1030, as shown in Figure 10. Memory 1010 would have read therein the top portions of the "X-scans", memory 1020 would have read therein the middle portions of the "X-scans", and memory 1030 would have read therein the bottom portions of the "X-scans". Each memory 1010, 1020 and 1030 has its own associated DMA and DSP, in a manner shown in Figure 11, to allow for parallel processing of the image data from the CCD cameras 510A - 510C, which is output to the decoder unit 540 in a faster manner than if only one memory was shared by the three cameras 510A - 510C.

In the first embodiment, the number of cameras required to cover a particular image region is preferably determined based on a 5% overlap region between cameras, but any particular value can be utilized while remaining within the scope of the invention as described herein.

Figure 12 is a block diagram of a raster conversion implementation that may be utilized in the first embodiment. In Figure 12, DSP 930 receives a interrupt signal from logic circuit 810, where the interrupt signal is based on a frame clock signal received by logic circuit 810. DSP 930 also receives a high speed clock, which corresponds to a 60 MHz clock in Figure 12. DSP 930 outputs addresses to a first and a second dynamic RAM (DRAM) 820A, 820B on address bus 830, based on an X pattern to be read out of DRAMs 820A, 820B via data bus 840. The output of CCD Camera is initially stored in an even frame FIFO 850 and an odd frame FIFO 860, based on which frame is currently being output from the camera. The camera data is output to DRAMs 820A, 820B via a bus

865. DRAM 820A receives the even frames from even frame FIFO 850, and second DRAM 820B receives the odd frames from odd frame FIFO 860. DRAMS 820A and 820B are written into at a rate determined by the frame clock. The outputs of first and second DRAMS 820A, 820B are sent to FIFOs 870A - 870D, and each FIFO is capable of supporting a separate line scanning camera. In an exemplary configuration, each FIFO is clocked at a rate of 2.048 MHz, and each FIFO provides an interrupt signal to DSP 930. FIFOs 870A - 870D provide an X-pattern of barcode data to decoder unit 540 (not shown in Figure 12).

A second embodiment of the invention will now be explained with reference to Figures 13 and 14. In Figure 13, instead of the laser light sources and CCD-based cameras being positioned in a gap beneath the conveyors 610, 620, a laser light sources 520A' and a CCD-based camera 510A' are instead positioned above a conveyor 650. In the second embodiment, the laser light source 520A' is positioned to output light towards a top surface of the conveyor 650. Before any object travelling on the conveyor 650 passes through a region covered by the laser light source 520A', it first passes through a height measuring unit 680, which determines a height of the object. The height measuring device may be constructed as a light curtain array or other type of height measuring device. A light curtain array that can be utilized in the system according to the second embodiment is disclosed in U.S. Patent Application 08/507,625, filed July 26, 1995, of Mark Woodworth, and assigned to PSC Inc., which is incorporated in its entirety herein by reference.

The height measuring unit 680 outputs a signal on line 513 to a processing unit 685, where the signal 513 is indicative of the height of an object passing by the height measuring unit 680. Based on the signal 513 received from the height measuring unit 680, the processing unit 685 outputs a first signal 515 to position the optics 688, and outputs a second signal 517

to position the laser light source 520A'. As is known to one of ordinary skill in the art, the laser light source 520A' is provided with a cylindrical lens (not shown), so as to change a "dot" of light output from the laser into a "line" of laser light. Based on the second signal 517, the laser light source 520A' is rotated to a position so as to shine light optimally onto the top surface of the object on the conveyor. Based on the first signal 515, the optics 688 provided for the CCD-based camera 510A' moves either upward or downwards, so as to properly focus the return light from a particular distance, with that particular distance corresponding to the top surface of the object passing beneath the CCD-based camera 510A'.

As shown in Figure 13, both the CCD-based camera 510A' and the laser light source 520A' are positioned on a housing 681 that is in the form of a U-shape on the conveyor 650. Optics 688 are slidably attached to a structure 511, where optics 688 either move up or down on the structure 511 depending on the signal 515 output from the processing unit 685. Laser light source 520A' is rotatably positioned based on the signal 517 output from the processing unit 685. Other types of configurations for providing movement of optics with respect to a stationary CCD-based camera may be utilized while remaining within the scope of the invention as described herein. For example, the optics 688 may be included in a lens portion of the CCD-based camera 510A', which is rotated either clockwise or counterclockwise in order to be focused to a particular distance from the CCD-based camera 510A'.

Figure 14 shows a first line 692 corresponding to an object having a first height, and a second line 693 corresponding to an object having a second height smaller than the first height. When an object having the first height passes by the height measuring unit 680, a signal 513 is output from the height measuring unit 680 to the processing unit 685 which is indicative of the first height. Based on the current speed of the conveyor and



the distance that the height measuring unit 680 is from the area where the laser light source 520A' and CCD-based camera 510A' are disposed (both known to the processing unit 685), the processing unit 685 can readily determine a time when the object having the first height will pass beneath the laser light source 520A' and CCD-based camera 510A'. Before this time, the processing unit 685 outputs the first and second signals 515, 517, so as to correctly position the laser light source 520A' and the optics 688 provided between the CCD-based camera 510A' and the conveyor 650. The position of the laser light source 520A' and the position of the optics 688 for an object having a height corresponding to line 692 are shown by the standard lines in Figure 14. With this positioning, the system according to the second embodiment is ready to read a bar code label or other information on the top surface of the object beneath it, with that top surface corresponding to the first line 692. Rotational movement of the laser light source 520A' is shown by the double-sided arrow 503 in Figure 13, and linear movement of the optics 688 is shown by the double-sided arrow 506 in Figure 13.

After the first object passes beneath the system according to the second embodiment, the system can then be repositioned for another object, such as a second object that has a second height as given by the second line 693. The height of the second line 693 is determined by the height measuring unit 680, and this information is sent to the processing unit 685. In this case, the laser light source 520A' is rotated downwardly (to a position shown by phantom lines in Figure 13) so that it shines light onto a region around the second line 693, and the optics 688 is moved upwardly (to a position shown by phantom lines in Figure 14) so as to adjust the focusing point of the light collection system to be at or around the second line 693.

Thus, in the second embodiment, the system maintains a same resolution for objects that have differing

heights, and thus are different distances away from the system. While the description was given for a system disposed directly above a conveyor, the system according to the second embodiment may also be utilized for other positions around the conveyor, such as to a side of a conveyor. In that case, the distance that the object is with respect to the side of the conveyor can be determined prior to the object passing by the scanning system, such as in a manner disclosed in U.S. Patent Application 08/507,625. The system according to the second embodiment provides an autofocusing for objects as they pass by, based on rotational movement of laser light sources and linear movement of optics provided for CCD-based cameras. Another type of autofocusing system is described in U.S. Patent 5,317,166, issued to Benny Tafoya, and assigned to PSC Inc., which is incorporated in its entirety herein by reference. In the system of U.S. Patent 5,317,166, however, there is no use of CCD-based cameras, such as in the present invention. Although the second embodiment is described and shown in the figures with respect to the use of one laser light source and one CCD-based camera, the system may also be configured with a plurality of laser light sources and CCD-based cameras, with each pair covering a particular widthwise area on the conveyor. With this configuration, labels on the top as well as the sides of an object passing below the laser light sources and CCD-based cameras may be read and decoded.

A third embodiment of the invention will now be explained with reference to Figures 15-17. In Figure 15, subsets of the pixel data from a CCD camera 1110 are provided to axis controllers 1120-1 to 1120-n, via a common logic unit 1170. The pixel data that is temporarily stored in Common Logic Unit 1170 is the result of return light from a particular region covered by the CCD camera 1110. As shown in Figure 15, an object 1101 is within the particular region covered the CCD camera 1110.

CCD camera 1110 is capable of outputting a matrix array of data at periodic instants in time, and thus corresponds to a two-dimensional CCD camera. The array may be an  $n \times n$  array, or an  $m \times n$  array of pixel elements, where  $m$  and  $n$  are integers. Common logic unit 1170 provides the logic for temporarily storing data from the CCD camera head 1110, and may be configured as a plurality of buffers 1400-1 to 1400- $n$  that are clocked by a clock signal 1420 to receive data from the CCD camera head 1110, as in Figure 16.

In the second embodiment, common logic unit 1170 includes a 1028-bit  $\times$  1028-bit memory array, which stores pixel data from the CCD camera 1110 at periodic time instants. The memory array may be configured as a plurality of buffers, as shown in Figure 16, or it may be configured as a random access memory that is updated at periodic instants in time, or by any other temporary storage device, as is known to one of ordinary skill in the art.

A master CPU 1130 initializes each of the axis controllers 1120-1 to 1120- $n$ , so that each axis controller extracts "pertinent data" of the pixel data read by the CCD cameras on each scan, and stores the pertinent data into a proper location in a corresponding axis memory 1150-1 to 1150- $n$ . As shown in Figure 15, each axis 1255-1 to 1255- $n$  has an associated axis controller, an associated axis memory, an associated bit logic unit, and an associated slave processor. Each axis 1255-1 to 1255- $n$  may be configured as a separate axis card, as shown by the dashed lines in Figure 15.

The master CPU 1130 loads each axis controller with a reload value that will cause a trigger to be generated by a counter (not shown) internal to each axis controller, at the proper rate for each scan on that axis. Each counter is initially loaded with a count that ensures the proper delay for the first detection. For example, a 45-degree axis controller will trigger on the first data bit on the first linear scan line, the second

data bit on the second linear scan line, the third linear data bit on the third linear scan line, etc. Since parts of many 45-degree scans will be found on the scan line, the counter will ensure that they are found at regular intervals after the first scan.

Next, the repeat count for each axis controller is initialized by the master CPU 1130. On certain scan lines, such as horizontal scan lines, it is necessary to write sequential points on the same line. For this reason, some of the axis controllers 1120-1 - 1120-n have a counter that causes sequential writes to occur following a trigger. This function is initialized prior to a scan.

Next, each axis has its associated scan counter initialized. The first trigger point a given axis find on any given line may not be the zeroth scan for that axis. For example, the first data point on the first scan will be used by the 45 degree axis controller, but may not necessarily be the first 45 degree scan. It may, however, become the center scan when the generation is complete. For this reason, the number of the first scan must be loaded prior to initiation of the scanning operation.

When a scan is initiated, a 1028 by 1028 array of pixel data is received from the read head of the CCD camera 1110. As the data is returned from the read head of the CCD camera 1110, a position clock is returned as well. This position clock is used to advance the counter of each of the axis controllers. The position clock is used to determine which scan the data currently stored in the common logic unit 1170 corresponds to.

When a counter for any of the axis controllers 1120-1 - 1120-n is triggered, the following steps occur, as shown in Figure 17. In a first step S1, the counter for each axis controller sequentially addresses the temporarily-stored data in the common logic unit 1170 via the select line 1410, as shown in Figure 16. A counter for reading data into the corresponding axis memory is

initialized to zero on a read operation that follows the scan.

5 In a second step S2, an axis memory 1150-1 - 1150-n associated with the axis controller is addressed by the axis controller to determine which scan is being written, and to determine where in the scan the bit belongs.

10 In a third step S3, data from predetermined memory locations (or buffers) returned from the read head of the CCD camera 1110 are now written sequentially into the axis memory.

15 In a fourth step S4, the contents of the common logic unit 1170 are incremented by one and rewritten. If an axis controller is not required to write multiple sequential locations from a same scan line, the scan counter associated with the axis controller is incremented. It now addresses the next location in the scan memory, and is ready for the next trigger. In the event that a multiple write is required, the write is repeated each clock period until the required number of  
20 writes takes place. The scan counter is then updated.

25 In a fifth step S5, the master CPU 1130 initiates a read cycle. In the second embodiment, no memory refresh cycle is required, as the data is read only once, and this will take place within the maximum refresh period for the memory.

30 During the read cycle that takes place during the fifth step S5, a bit logic unit 1180-1 to 1180-n for each axis will rapidly read all sequential memory locations within it associated the axis memory. As each location is read, a count is generated of the time since the last data transition. Each time a data transition is detected, the count since the last transition is passed to an associated slave processor 1160-1 to 1160-n.

35 Each slave processor 1160-1 to 1160-n utilizes the information retrieved from its corresponding bit logic unit 1180-1 to 1180-n in order to determine if a potentially valid bar code may have been read. This determination is based on known characteristics of bar

code labels, such as quiet zone size, minimum width and maximum width bar code sizes, etc. If the information retrieved from the corresponding bit logic unit is such that the data cannot correspond to a true bar code, then  
5 that data is not sent to the master CPU 1130 for decoding. If, however, the data can possibly be a true bar code, then that data is sent to the master CPU 1130 for decoding.

Each slave processor 1160-1 - 1160-n is polled by the  
10 master CPU 1130 in a periodic manner, and if a potential bar code has been located, it will be passed to the master CPU 1130 for decoding. Each slave processor is connected to its corresponding bit logic unit 1180-1 - 1180-n, which is itself connected to its corresponding  
15 axis memory 1150-1 - 1150-n. In the third embodiment, each bit logic unit 1180-1 - 1180-n corresponds to a first-in, first-out buffer (FIFO), where bar widths and bar spaces are stored as 8-bit wide elements in the 9-bit x 256-bit FIFO. That is, consecutive ones correspond to  
20 a particular bar width, and consecutive zeros correspond to a particular space width. The ninth bit for each storage location in the bit logic unit corresponds to a quiet-zone bit. The quiet-zone bit indicates whether or not a quiet-zone has been scanned. Other configurations  
25 of the bit logic unit may be envisioned by one of ordinary skill in the art, while remaining within the scope of the invention as described herein.

During intervals in which no bar codes are detected, the master CPU 1130 will place all axis controllers in a  
30 "horizontal" mode, and may initiate practice scans with artificial data, if desired. The slave processors 1160-1 to 1160-n will verify that all of the data is correct, and report this to the master CPU 1130. Both the slave processors 1160-1 to 1160-n and the master CPU 1130 may  
35 run internal diagnostics when not actively scanning the read data.

As shown in Figure 15, both the slave processors 1160-1 to 1160-n and the master CPU 1130 have a

corresponding parallel input/output (PIO) port, for transmitting and receiving data between the master CPU and the slave processor. The master CPU 1130 sends control signals to the common logic unit 1170 via another  
5 PIO port, and communicates with a host CPU (not shown) and an auxiliary port (not shown) via a serial input/output (SIO) port.

Referring now to Figure 16, each buffer of the common logic unit 1170 is sampled based on a select signal and a clock signal. For example, for a 45 degree scan line, the leftmost buffer 1400-1 on the top row is sampled at a time  $t_0$  and output to the axis controller for the 45 degree axis, the next-to-leftmost buffer 1400-( $m+2$ ) on the second row is sampled at a time  $t_{m+2}$  and output to the  
15 axis controller for the 45 degree axis, and so on. The sampling of each of the buffers is performed at a fast enough rate so that all of the buffers are sampled prior to a next scan (and therefore reloading) of data into the common logic unit 1170. For a horizontal scan line,  
20 each of the buffers in the top-most row are sampled consecutively, with the sampled data being forwarded to the axis memory of the horizontal axis. Of course, other horizontal scan lines may also be created at the same time, by taking data from each of buffers in other row of the common logic unit 1170. Thus, for the 45 degree scan  
25 line, the count value of "1" causes the output of the buffer 1400-1 to be sent to the axis controller for the 45 degree scan line, the count value of " $m+2$ " causes the output of the buffer 1400-( $m+2$ ) to be output to the axis  
30 controller for the 45 degree scan line, and so on. Each buffer is separately addressable based on a current state of the multi-bit select line 1410, and each buffer is clocked to receive new data from the CCD-based camera 1110 based on the clock signal line 1420.

35 The "count" for each axis is different based on the scan line to be created for that axis. The count progresses from left to right, starting at the topmost row of the buffers in the common logic unit 1170, and

proceeding down to the rightmost buffer in the last row of the common logic unit 1170. The count is completed (e.g., select line 1410 transitions from 0 to n in units of 1) prior to data from a next scan being written into the buffers. Data is read into the buffers at a time corresponding to a next clock pulse on the clock line 1420. The clock rate is thus slower than the select rate, and in the third embodiment is at least  $1/n$  as slow.

10       The third embodiment is described having n axes, with n being an integer value that corresponds to the number of simultaneous different scan lines that are created from the data output from the CCD-based camera 1110. The value n may be preset to a value, such as 16, or it may be set to a value based on a particular bar code to be detected and decoded. For example, the number of different scan lines may be set based on the minimum height of a bar of a bar code label, with more scan lines being utilized for a smaller minimum-height bar code label. In the third embodiment, a bar code label may be decoded irrespective as to the orientation of the bar code label with respect to the CCD-based camera 1110, since a plurality of different virtual scan lines are created from the two-dimensional array of pixel data output by the CCD-based camera 1110.

25       While embodiments have been described herein, modification of the described embodiments may become apparent to those of ordinary skill in the art, following the teachings of the invention, without departing from the scope of the invention as set forth in the appended claims. For example, the second embodiment can be utilized with a "rematch" technique for determining bar codes based on partial scans of a bar code label, as described in U.S. Patent Number 5,481,097, issued to Benny R. Tafoya, which is assigned to PSC Inc., and which is incorporated in its entirety herein by reference. In the rematch technique, two separate scan lines are utilized to decode a bar code label, where data from one



scan line is used to decode a first portion of the label, and where data from the other scan line is used to decode a remaining second portion of the label.

What Is Claimed Is:

1. A bar code scanning system, comprising:
  - a first conveyor for moving objects from a first location to a second location;
  - a second conveyor for receiving the objects from the first conveyor and for moving the objects to a third location;
  - a light emitting device positioned in a gap underneath a top surface of the first and second conveyors, the light emitting device configured to shine light onto bar code labels on a bottom side of objects as the objects traverse from the first conveyor to the second conveyor;
  - a light receiving device positioned in the gap, the light receiving device configured to receive reflected light from the bottom side of the objects due to the light being shined on the objects by the light emitting device; and
  - a plate disposed entirely within the gap, the mirror-like unit having a top surface disposed along a same plane as the top surfaces of the first and second conveyors,wherein the top surface of the plate provides a substantially continuous surface with the top surfaces of the first and second conveyors as the objects traverse from the first location to the third location.
2. The bar code scanning system according to claim 1, wherein the plate provides a magnification to the light output by the light emitting device and the received light directed to the light receiving device.
3. The bar code scanning system according to claim 2, wherein the light receiving device comprises at least one CCD camera having a plurality of pixel elements, each pixel element receiving light from a predetermined region on the top surface of the plate.

4. The bar code scanning system according to claim 3, wherein the plate is comprised of one of glass and plastic.

5. The bar code scanning system according to claim 4, wherein a width of the top surface of the plate is such that the at least one CCD camera, by itself, is not able to receive light from all regions of the top surface of the window-like surface, and

wherein the magnification provides compensation such that the at least one CCD camera is able to receive light from all regions of the top surface of the plate.

6. The bar code scanning system according to claim 5, further comprising:

a first light emitting unit and light receiving unit pair disposed to detect a bar code label on a front side of the objects as the objects traverse along the first and second conveyors, the front side being with respect to a direction of movement of the objects;

a second light emitting unit and light receiving unit pair disposed to detect a bar code label on a rear side of the objects as the objects traverse along the first and second conveyors, the rear side being with respect to the direction of movement of the objects;

a third light emitting unit and light receiving unit pair disposed to detect a bar code label on one side of the objects as the objects traverse along the first and second conveyors, the one side being substantially perpendicular with respect to the top surfaces of the first and second conveyors;

a fourth light emitting unit and light receiving unit pair disposed to detect a bar code label on another side of the objects as the objects traverse along the first and second conveyors, the another side being substantially perpendicular with respect to the top surfaces of the first and second conveyors; and

a fifth light emitting unit and light receiving unit pair disposed to detect a bar code label on a top side of the objects as the objects traverse along the first and second conveyors,

wherein the light emitting device and the light receiving device together constitute a sixth light emitting unit and light receiving unit pair.

7. The bar code scanning system according to claim 6, wherein the bar code scanning system is capable of detecting a bar code label disposed anywhere on the objects as the objects traverse from the first location to the third location.

8. The bar code scanning system according to claim 1, wherein one of the first and second conveyors corresponds to a takeaway conveyor, and the other of the first and second conveyors corresponds to a feed conveyor.

9. A bar code scanning method, comprising the steps of:

a) scanning a particular location with a CCD camera having a plurality of pixels each positioned to receive reflected light from a distinct portion of the particular location;

b) providing separate control for a plurality of different scan lines to be generated;

c) outputting data from a different subsets of the plurality of pixels based on the separate control provided in the step b), so as to provide a plurality of virtual scan lines, respectively; and

d) determining if a bar code has been scanned by simultaneously decoding the data from each of the different subsets.

10. The method according to claim 9, wherein the separate control is provided by a master CPU providing a

count value to be used as a trigger for creation of each of the plurality of scan lines, the count value being used to receive only certain data from the CCD cameras that corresponds to certain pixels of the CCD camera.

11. The method according to claim 10, wherein the data for the plurality of subsets are respectively stored in axis memories before being read at period instants by a corresponding slave processor to determine if a possible bar code label has been scanned.

12. An apparatus for reading bar codes, comprising:  
a CCD camera configured to scan a particular location, the CCD camera having a plurality of pixels each positioned to receive reflected light from a distinct portion of the particular location;

a plurality of axis controllers respectively providing control for a plurality of different virtual scan lines to be generated;

a common logic unit configured to receive respective control signals from the plurality of axis controllers and to output data from different subsets of the plurality of pixels based on the control signals;

a plurality of axis memories connected to the common logic unit and configured to respectively receive the different subsets of the plurality of pixels output from the common logic unit; and

a plurality of slave processors connected to the plurality of axis memories and configured to periodically receive data stored respectively stored in the plurality of axis memories, each of the slave processors configured to determine if a possible bar code label has been scanned.

13. The apparatus according to claim 12, wherein the common logic unit comprises a plurality of buffers configured to receive and temporarily store pixel data from the CCD camera.

14. The apparatus according to claim 13, wherein the axis controllers provide for simultaneous creation of the plurality of virtual scan lines.

15. The apparatus according to claim 14, wherein the slave processors provide for simultaneous determination of data received from the plurality of virtual scan lines.

16. An apparatus for scanning a bar code label, comprising:

- a CCD camera configured to provide a linear array of scan output corresponding to a particular region currently being scanned;

- a memory for storing the linear array of scan output from the CCD camera;

- a controller connected to the CCD camera and configured to output the linear array of scan output to a particular region of the memory;

- a signal processor connected to the memory and configured to output data from particular memory locations of the memory so as to create at least one virtual scan line; and

- a decoder configured to determine if data corresponding to the virtual scan line corresponds to a real bar code.

17. The apparatus according to claim 16, further comprising a read-only-memory connected to the signal processor and configured to store an application program to be run by the signal processor, the application program providing the control by which the signal processor outputs the data from the particular locations of the memory.

18. The apparatus according to claim 17, wherein the virtual scan lines correspond to two 45 degree lines that

intersect with each other so as to form an X-shape scan pattern.

19. The apparatus according to claim 18, wherein the decoder is only capable of reading data corresponding to the X-shape scan pattern.

20. The apparatus according to claim 18, wherein the memory includes a row pointer that indicates whether a particular row of the memory has been read into by the linear array of scan output, and

wherein the row pointer is used by the signal processor as a timing signal in order to determine when to cause the output of the data from the particular memory locations of the memory.

21. A bar code scanning system for a conveyor, comprising:

a laser light source configured to output laser light, said laser light source being rotatably mounted to a housing;

a CCD-based camera configured to receive light from a particular region;

a lens disposed between the CCD-based camera and the conveyor, the lens being mounted to the housing and capable of linear movement with respect to the conveyor and the CCD-based camera;

a height measuring device configured to determine a height of an object as the object passes by the height measuring device and to output a height signal indicative thereof; and

a processing unit configured to output a first signal to rotate the laser light source to a first position and to output a second signal to linearly move the lens to a second position,

wherein the first and second positions are such that the laser light source and the CCD-based camera are

focused to an area corresponding to the height of the object.

22. The bar code scanning system according to claim 21, wherein the laser light source and the CCD-based camera are both positioned above the conveyor, and

wherein the laser light source outputs the laser light downwards towards a top surface of the conveyor, and the CCD-based camera receives the light reflected off of the object and directed upwards with respect to the conveyor.



**AMENDED CLAIMS**

[received by the International Bureau on 24 March 1999 (24.03.99);  
original claims 1-22 replaced by new claims 1-18 (6 pages)]

1. A bar code scanning system, comprising:
  - a first conveyor for moving objects from a first location to a second location;
  - a second conveyor for receiving the objects from the first conveyor and for moving the objects to a third location;
  - a light emitting device positioned in a gap underneath a top surface of the first and second conveyors, the light emitting device configured to shine light onto bar code labels on a bottom side of objects as the objects traverse from the first conveyor to the second conveyor;
  - a light receiving device positioned in the gap, the light receiving device configured to receive reflected light from the bottom side of the objects due to the light being shined on the objects by the light emitting device; and
  - a plate disposed entirely within the gap, the mirror-like unit having a top surface disposed along a same plane as the top surfaces of the first and second conveyors,wherein the top surface of the plate provides a substantially continuous surface with the top surfaces of the first and second conveyors as the objects traverse from the first location to the third location, and  
wherein the plate provides a magnification to the light output by the light emitting device and the received light directed to the light receiving device.
2. The bar code scanning system according to claim 1, wherein the light receiving device comprises at least one CCD camera having a plurality of pixel elements, each pixel element receiving light from a predetermined region on the top surface of the plate.
3. The bar code scanning system according to claim 2, wherein the plate is comprised of one of glass and plastic.

4. The bar code scanning system according to claim 3, wherein a width of the top surface of the plate is such that the at least one CCD camera, by itself, is not able to receive light from all regions of the top surface of the mirror-like unit, and wherein the magnification provides compensation such that the at least one CCD camera is able to receive light from all regions of the top surface of the plate.

5. The bar code scanning system according to claim 4, further comprising:

a first light emitting unit and light receiving unit pair disposed to detect a bar code label on a front side of the objects as the objects traverse along the first and second conveyors, the front side being with respect to a direction of movement of the objects;

a second light emitting unit and light receiving unit pair disposed to detect a bar code label on a rear side of the objects as the objects traverse along the first and second conveyors, the rear side being with respect to the direction of movement of the objects;

a third light emitting unit and light receiving unit pair disposed to detect a bar code label on one side of the objects as the objects traverse along the first and second conveyors, the one side being substantially perpendicular with respect to the top surfaces of the first and second conveyors;

a fourth light emitting unit and light receiving unit pair disposed to detect a bar code label on another side of the objects as the objects traverse along the first and second conveyors, the another side being substantially perpendicular with respect to the top surfaces of the first and second conveyors; and

a fifth light emitting unit and light receiving unit pair disposed to detect a bar code label on a top side of the objects as the objects traverse along the first and second conveyors,

wherein the light emitting device and the light receiving device together constitute a sixth light emitting unit and light receiving unit pair.

6. The bar code scanning system according to claim 5, wherein the bar code scanning system is capable of detecting a bar code label disposed anywhere on the objects as the objects traverse from the first location to the third location.

7. The bar code scanning system according to claim 1, wherein one of the first and second conveyors corresponds to a takeaway conveyor, and the other of the first and second conveyors corresponds to a feed conveyor.

8. A bar code scanning method, comprising the steps of:

a) scanning a particular location with a CCD camera having a plurality of pixels each positioned to receive reflected light from a distinct portion of the particular location;

b) providing separate control for a plurality of different scan lines to be generated;

c) outputting data from a different subsets of the plurality of pixels based on the separate control provided in the step b), so as to provide a plurality of virtual scan lines, respectively; and

d) determining if a bar code has been scanned by simultaneously decoding the data from each of the different subsets,

wherein the separate control is provided by a master CPU providing a count value to be used as a trigger for creation of each of the plurality of scan lines, the count value being used to receive only certain data from the CCD cameras that corresponds to certain pixels of the CCD camera, and

wherein the data for the plurality of subsets are respectively stored in axis memories before being read periodically by a corresponding slave processor to determine if a possible bar code label has been scanned.

9. An apparatus for reading bar codes, comprising:

a CCD camera configured to scan a particular location, the CCD camera having a plurality of pixels each positioned to receive reflected light from a distinct portion of the particular location;

a plurality of axis controllers respectively providing control for a plurality of different virtual scan lines to be generated;

a common logic unit configured to receive respective control signals from the plurality of axis controllers and to output data from different subsets of the plurality of pixels based on the control signals;

a plurality of axis memories connected to the common logic unit and configured to respectively receive the different subsets of the plurality of pixels output from the common logic unit; and

a plurality of slave processors connected to the plurality of axis memories and configured to periodically receive data stored respectively stored in the plurality of axis memories, each of the slave processors configured to determine if a possible bar code label has been scanned.

10. The apparatus according to claim 9, wherein the common logic unit comprises a plurality of buffers configured to receive and temporarily store pixel data from the CCD camera.

11. The apparatus according to claim 10, wherein the axis controllers provide for simultaneous creation of the plurality of virtual scan lines.

12. The apparatus according to claim 11, wherein the slave processors provide for simultaneous determination of data received from the plurality of virtual scan lines.

13. An apparatus for scanning a bar code label, comprising:

a CCD camera configured to provide a linear array of scan output corresponding to a particular region currently being scanned;

a memory for storing the linear array of scan output from the CCD camera;

a controller connected to the CCD camera and configured to output the linear array of scan output to a particular region of the memory;

a signal processor connected to the memory and configured to output data from particular memory locations of the memory so as to create at least one virtual scan line;

a decoder configured to determine if data corresponding to the virtual scan line corresponds to a real bar code; and

a read-only-memory connected to the signal processor and configured to store an application program to be run by the signal processor, the application program providing the control by which the signal processor outputs the data from the particular locations of the memory.

14. The apparatus according to claim 13, wherein the virtual scan lines correspond to two 45 degree lines that intersect with each other so as to form an X-shape scan pattern.

15. The apparatus according to claim 14, wherein the decoder is only capable of reading data corresponding to the X-shape scan pattern.

16. The apparatus according to claim 14, wherein the memory includes a row pointer that indicates whether a particular row of the memory has been read into by the linear array of scan output, and

wherein the row pointer is used by the signal processor as a timing signal in order to determine when to cause the output of the data from the particular memory locations of the memory.

17. A bar code scanning system for a conveyor, comprising:

a laser light source configured to output laser light, said laser light source being rotatably mounted to a housing;

a CCD-based camera configured to receive light from a particular region;

a lens disposed between the CCD-based camera and the conveyor, the lens being mounted to the housing and capable of either movement in a first direction towards the CCD-based camera or movement in a second direction towards the conveyor, wherein the movement causes the CCD-based camera to be focused to a location that is a particular distance away from the CCD-based camera;

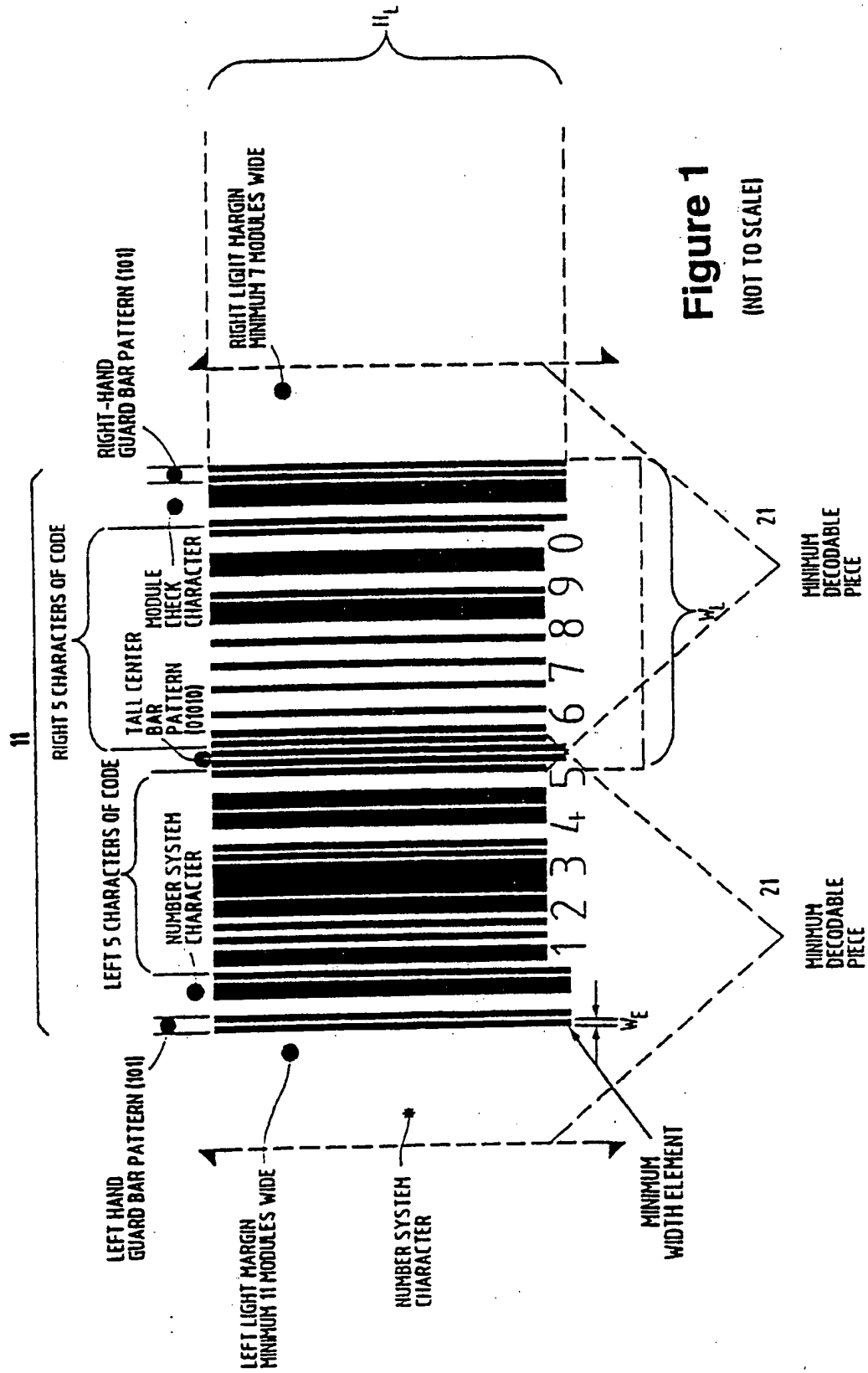
a height measuring device configured to determine a height of an object as the object passes by the height measuring device and to output a height signal indicative thereof; and

a processing unit configured to output a first signal to rotate the laser light source to a first position and to output a second signal to linearly move the lens to a second position,

wherein the first and second positions are such that the laser light source and the CCD-based camera are focused to an area corresponding to the height of the object.

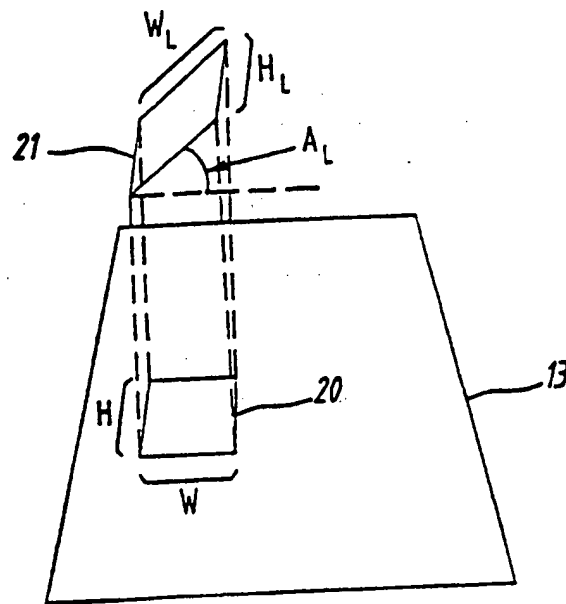
18. The bar code scanning system according to claim 17, wherein the laser light source and the CCD-based camera are both positioned above the conveyor, and

wherein the laser light source outputs the laser light downwards towards a top surface of the conveyor, and the CCD-based camera receives the light reflected off of the object and directed upwards with respect to the conveyor.



**Figure 1**  
(NOT TO SCALE)

Figure 2





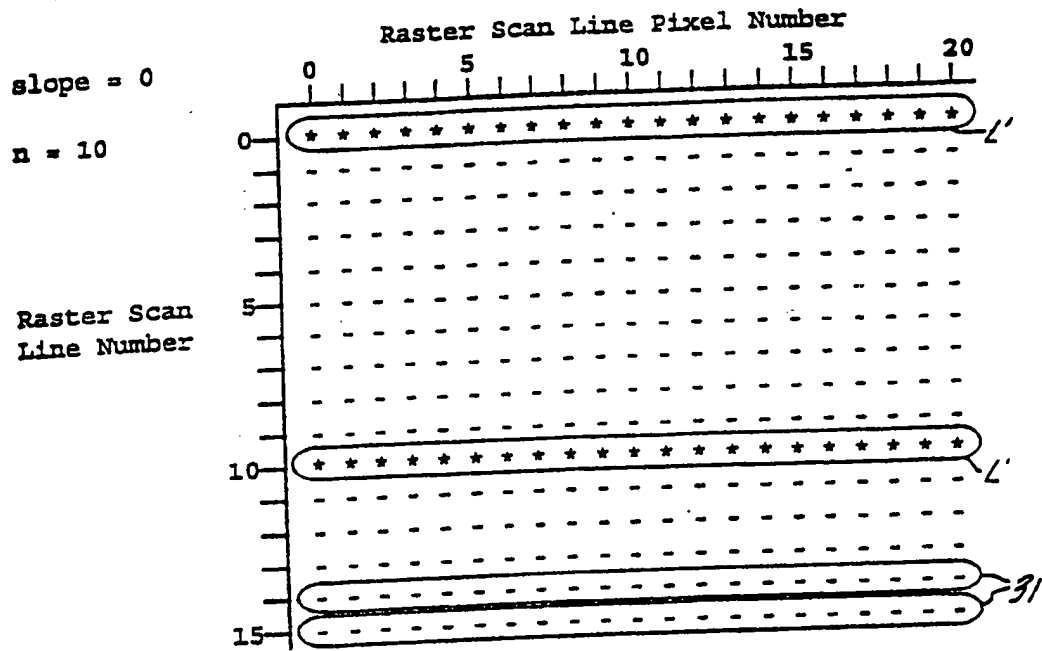


Figure 3A

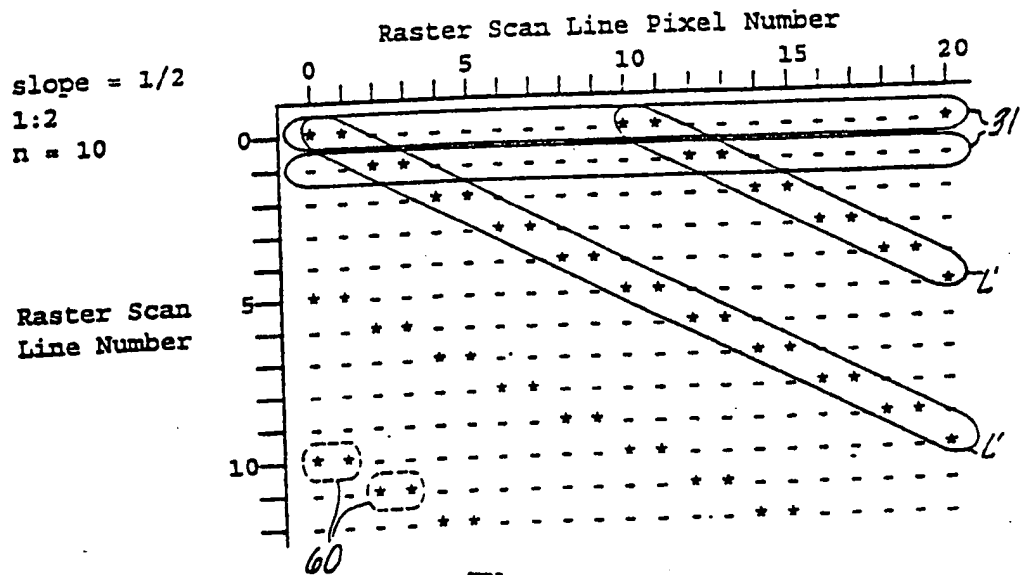
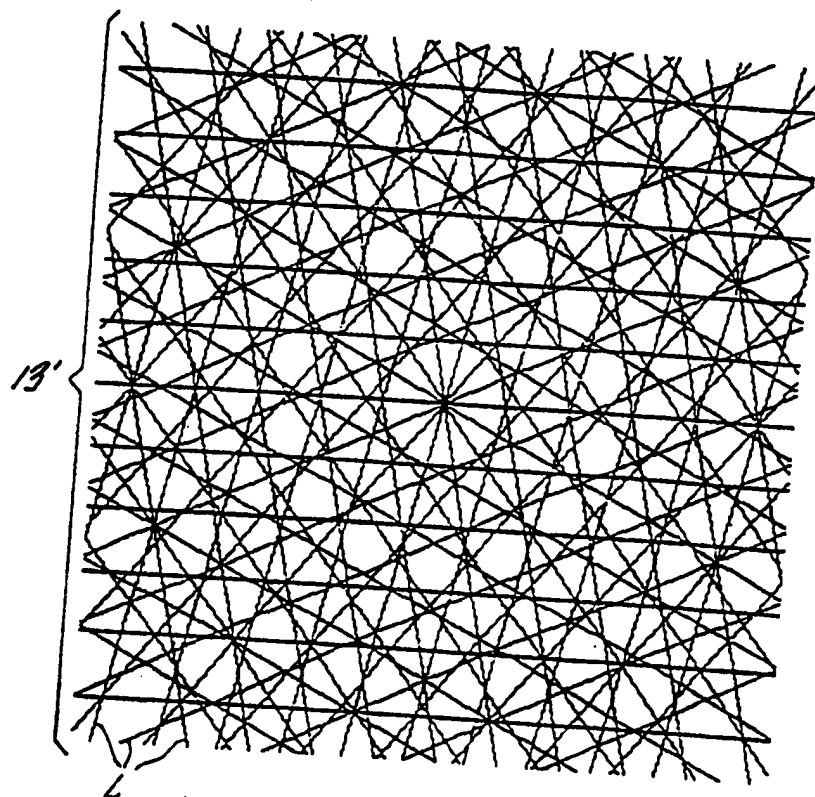


Figure 3B

**Figure 4**

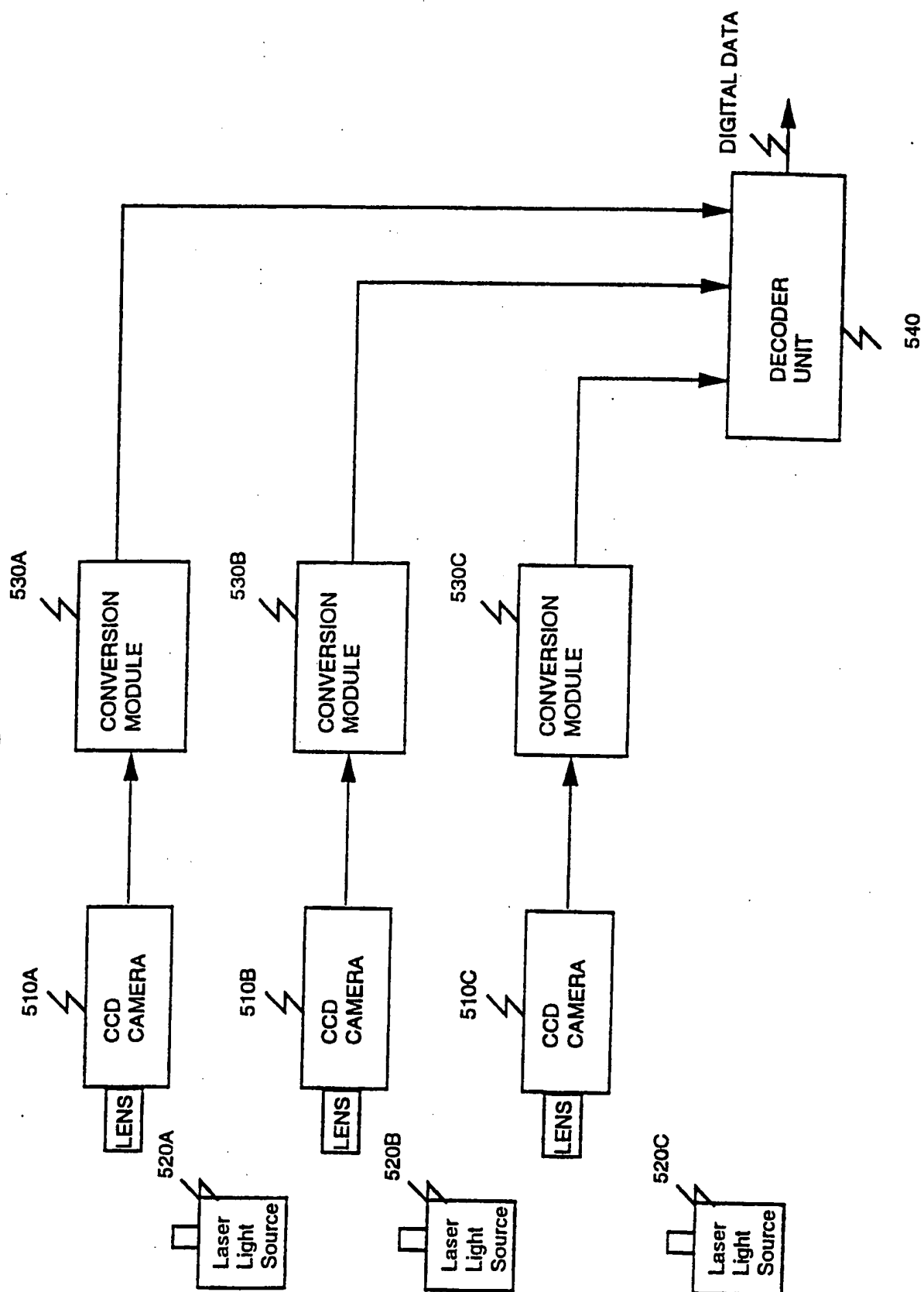
**Figure 5**

Figure 6

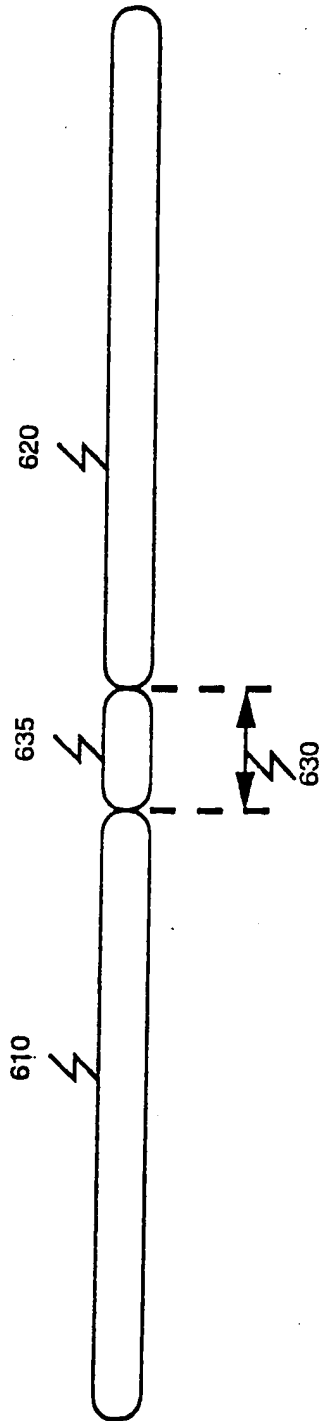


Figure 7

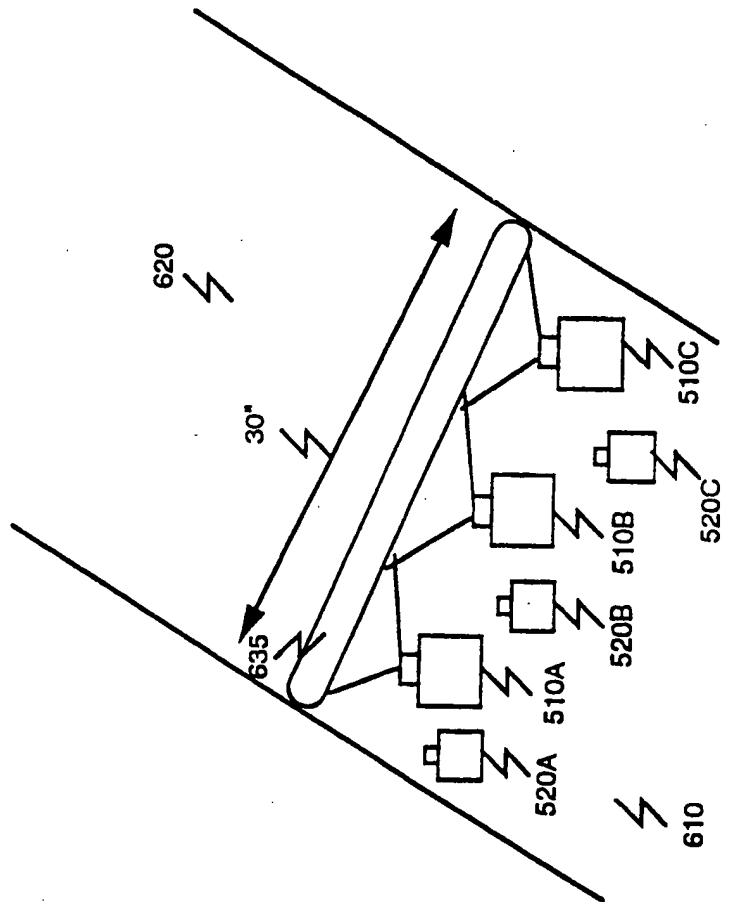


Figure 8

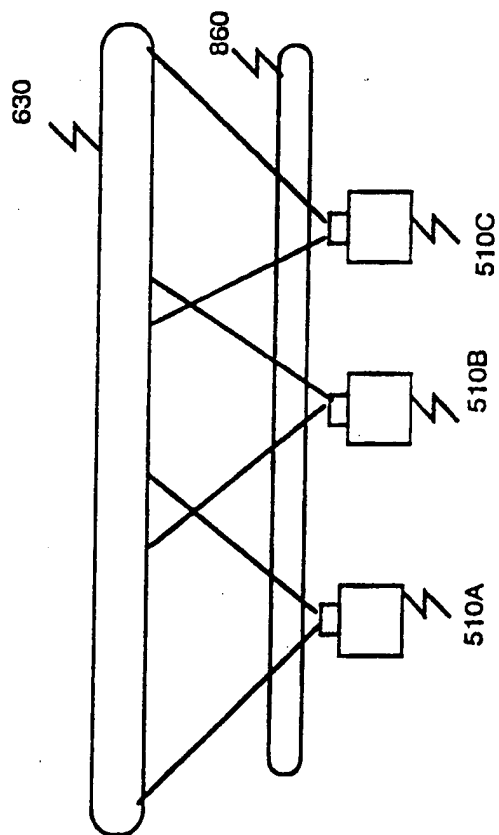
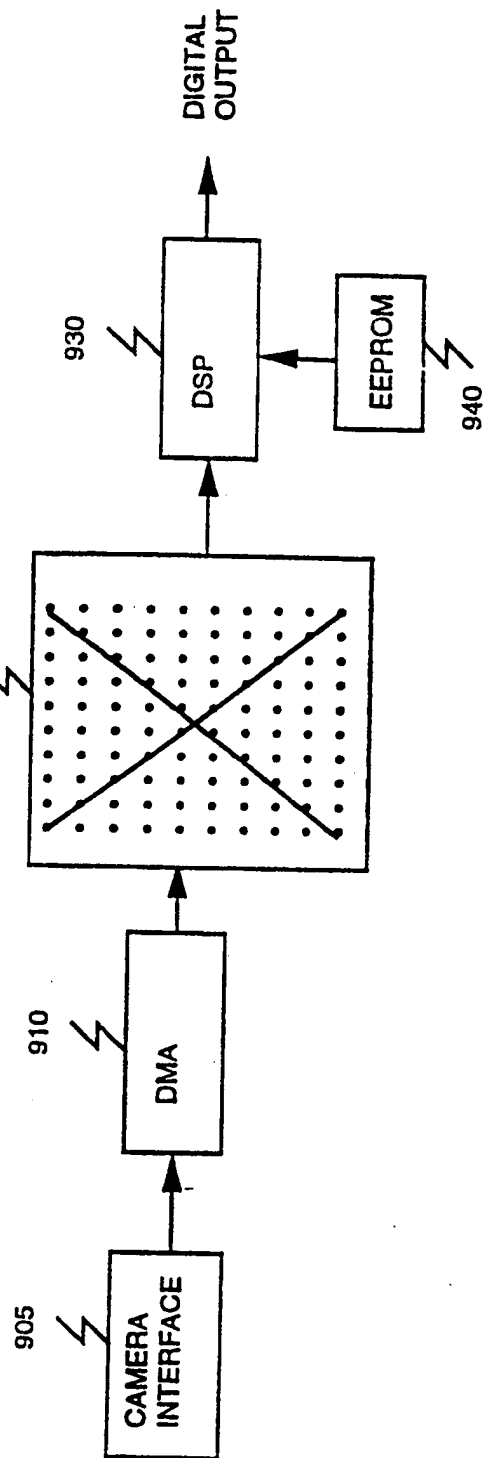


Figure 9



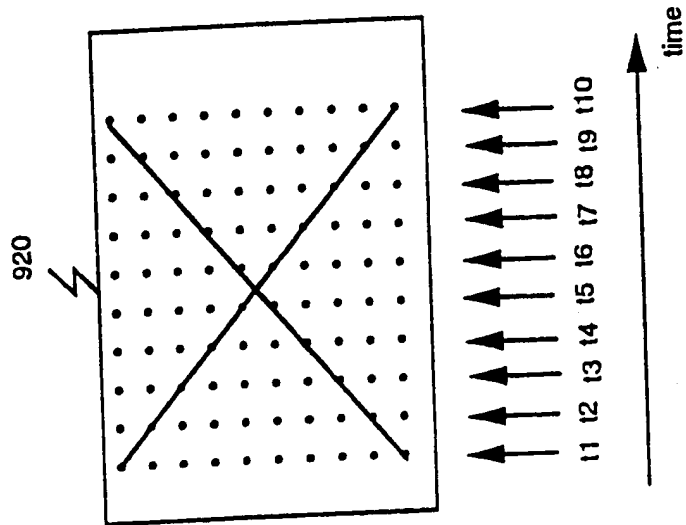
**Figure 10**

Figure 11

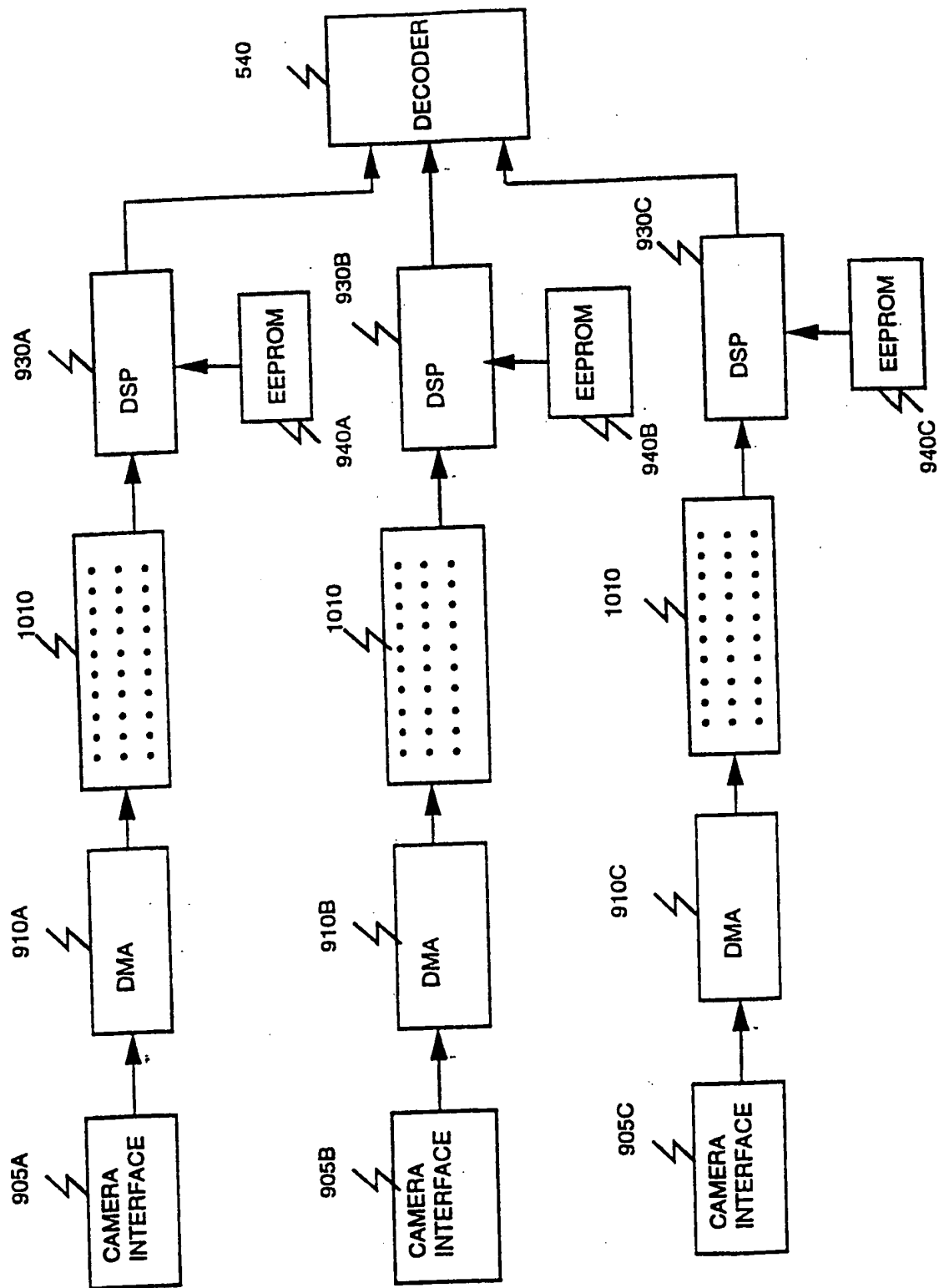
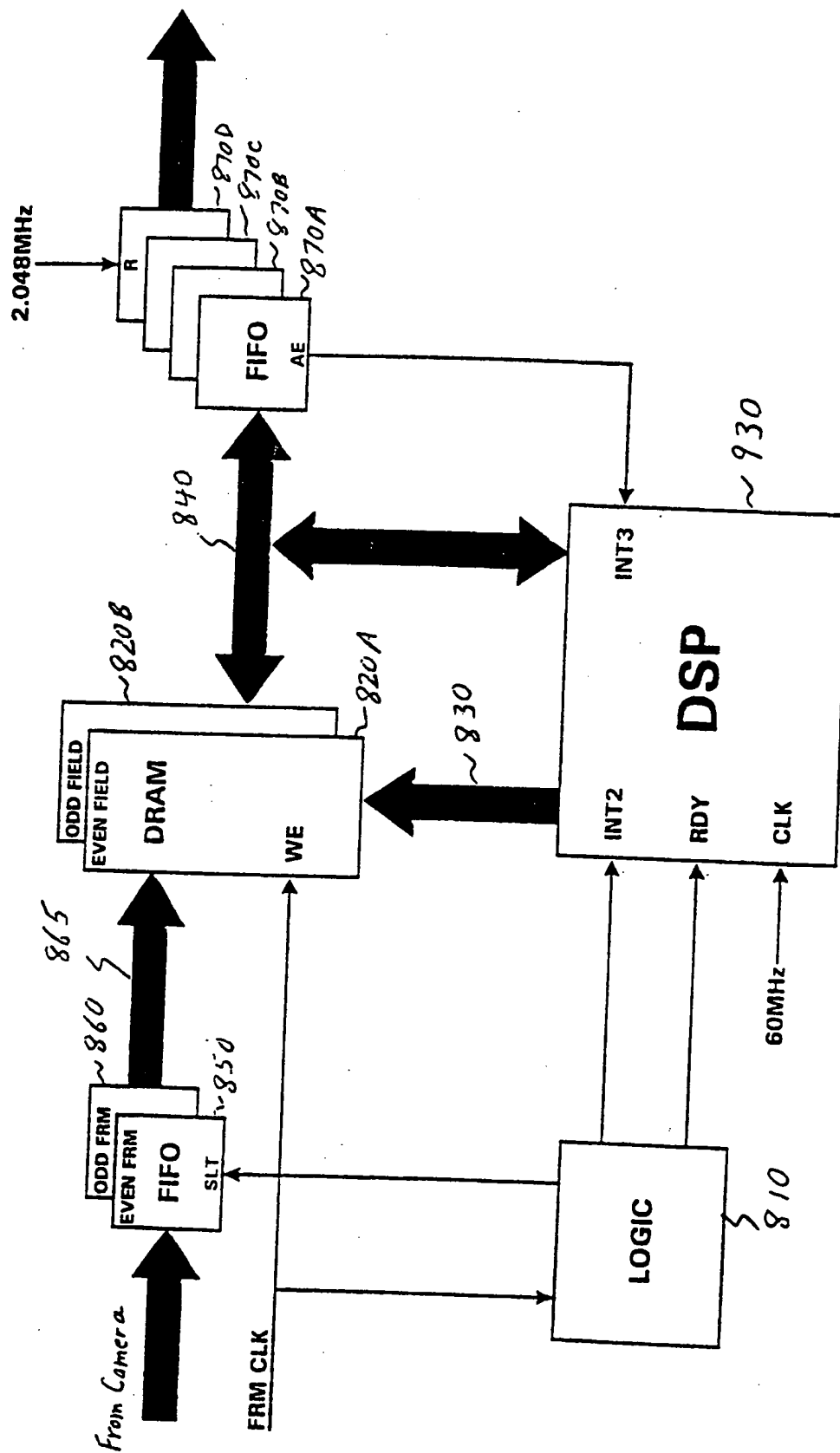


Figure 12







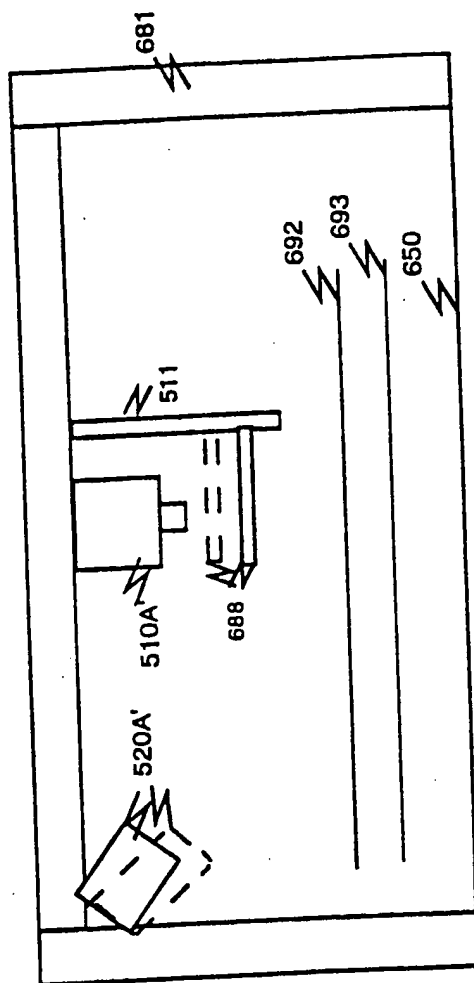
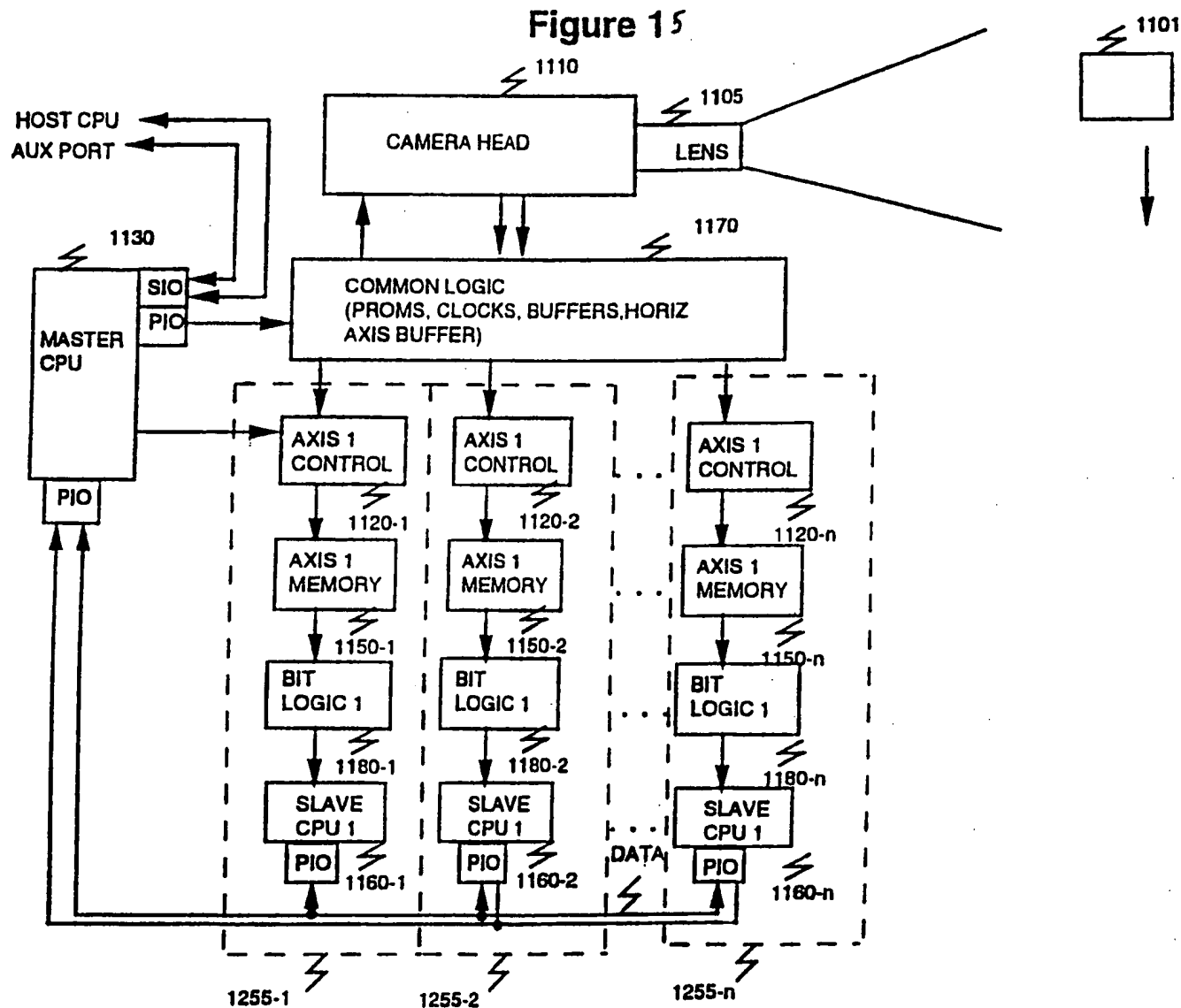
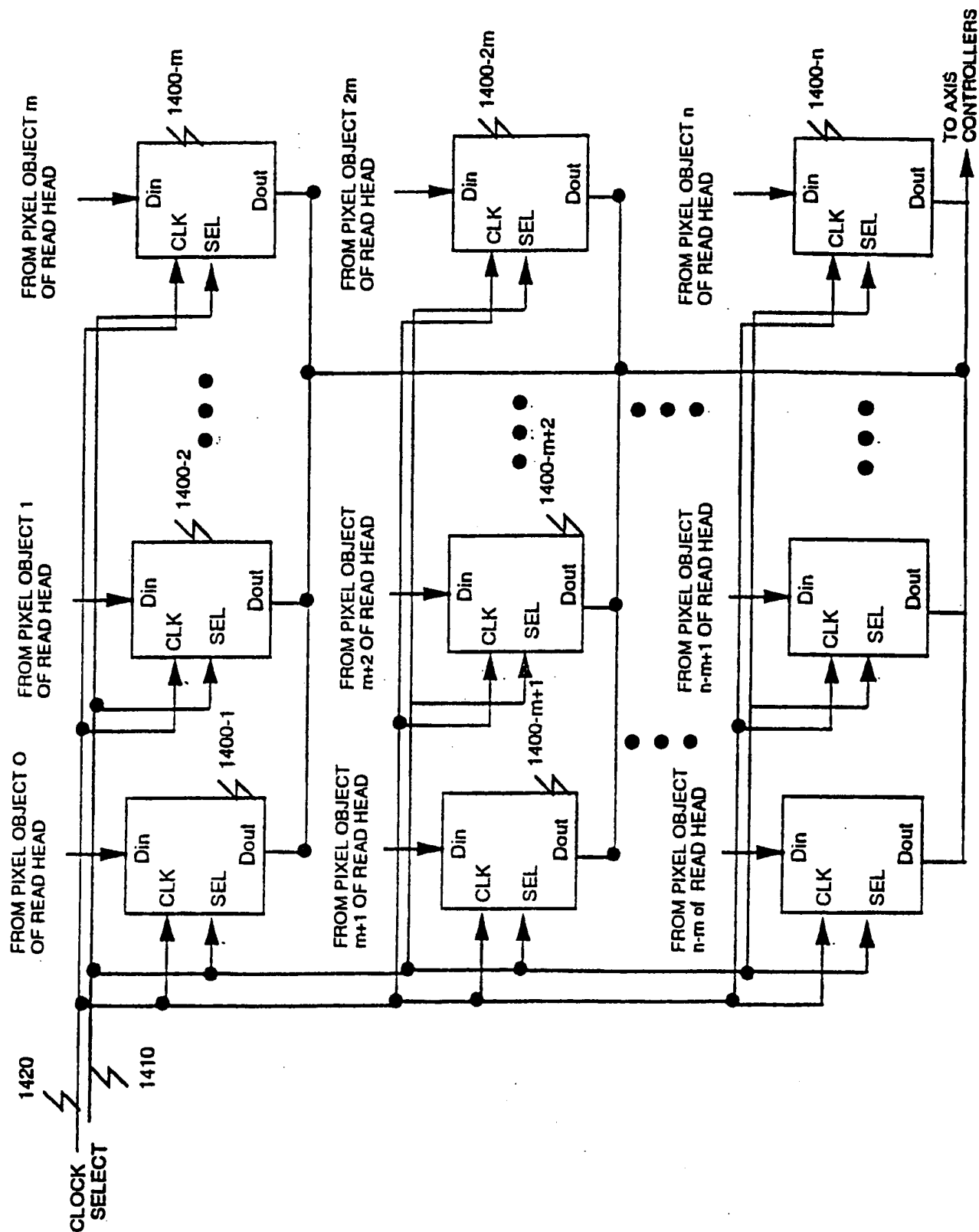
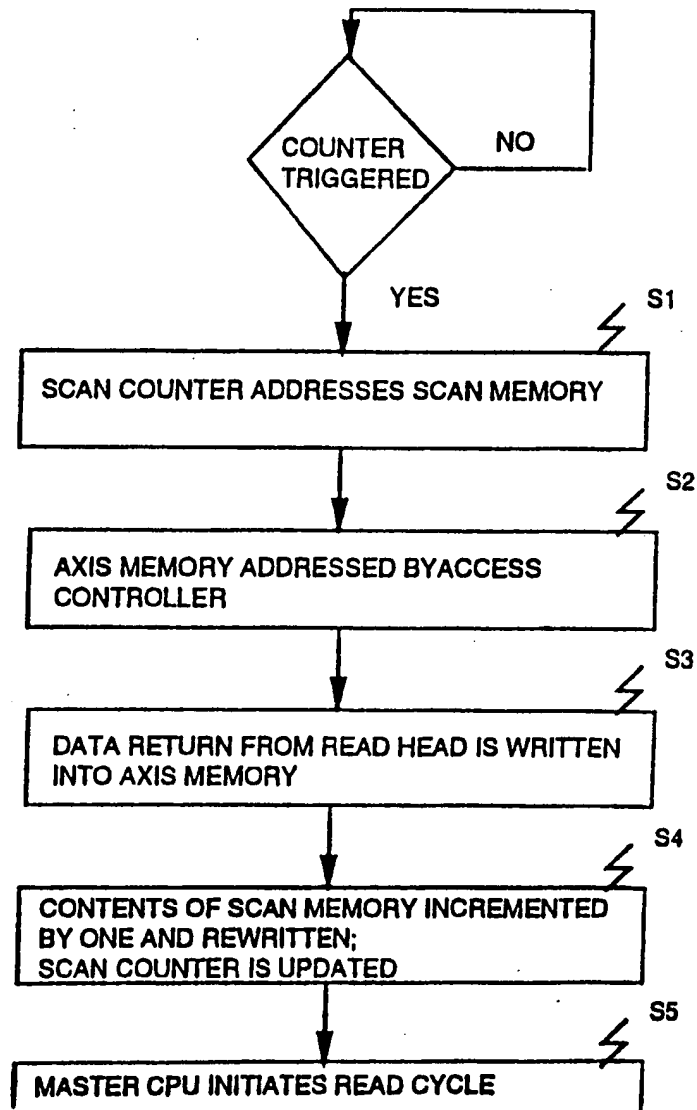
**Figure 14**

Figure 15



## Figure 16



**Figure 17**

## INTERNATIONAL SEARCH REPORT

International application No.

PCT/US98/22638

**A. CLASSIFICATION OF SUBJECT MATTER**

IPC(6) :G06K 7/10

US CL :235/462.17

According to International Patent Classification (IPC) or to both national classification and IPC

**B. FIELDS SEARCHED**

Minimum documentation searched (classification system followed by classification symbols)

U.S. : 235/462.17, 462.22, 462.27

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

None

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

APS search term: conveyer and bar code

**C. DOCUMENTS CONSIDERED TO BE RELEVANT**

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X --- Y	US 5,252,814 A (TOOLEY) 12 October 1993 (12.10.1993), col. 5, lines 49-64.	1,8 --- 2-7, 9-22
Y	US 5,635,699 A (CHERRY et al) 3 June 1997 (3.6.1997), col. 5, lines 35-62.	2-7, 9-22
Y	US 3,774,014 A (BERLER) 20 November 1973 (20.11.1973), col. 5, lines 44-64.	6,7



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents:	"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
"A" document defining the general state of the art which is not considered to be of particular relevance	"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"E" earlier document published on or after the international filing date	"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"&" document member of the same patent family
"O" document referring to an oral disclosure, use, exhibition or other means	
"P" document published prior to the international filing date but later than the priority date claimed	

Date of the actual completion of the international search

02 JANUARY 1999

Date of mailing of the international search report

28 JAN 1999

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